

Dominance move: concept, advances and applications in multi- and many-objective optimization problems

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May-2021

1. Introduction
2. Introduction
3. Introduction
4. Related works
5. DoM assignment formulation and MIP-DoM
6. Experiments
7. Conclusion
8. Future research and final comments
9. References

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

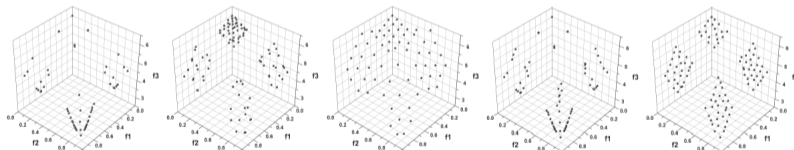
Experiments

Conclusion

Future research and
final comments

References

- Multi-objective and many-objective problems are common in real cases;
- How to summarize approximation sets, taking into account:
 - Location;
 - Shape;
 - Distribution.



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

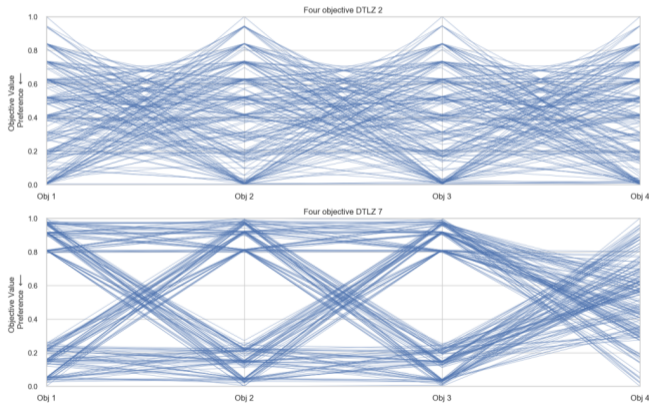
Experiments

Conclusion

Future research and
final comments

References

■ Graphical techniques: multi-objective problems;



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

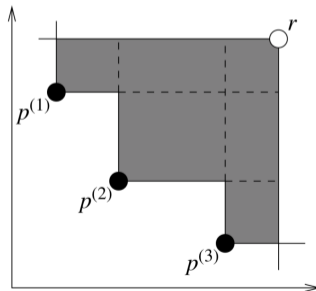
Experiments

Conclusion

Future research and
final comments

References

- **Quality indicators:** multi-objective and many-objective problems;
- Some well know quality indicators: Hypervolume, IGD and ϵ -indicators;
- Most quality indicators have drawbacks: reference point, reference sets, sensitive to extreme point, lack of information, computational cost, and others;



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

- Dominance Move (DoM) is a new binary quality indicator:
 - It does not require any pre-defined set of points, such as, a reference point or a reference set;
 - It is not affected by dominance resistant solutions, unlike that in HV;
 - There is no lack of information, such as in ϵ -indicators.
- DoM calculates the minimum total move of members of one set so that all elements in another set are to be dominated or identical to at least one member of the first set.

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

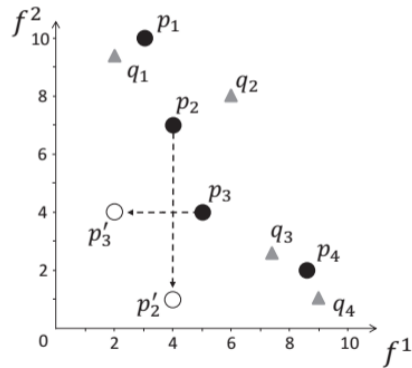
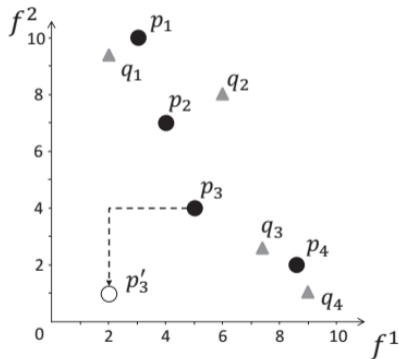
Experiments

Conclusion

Future research and
final comments

References

Example $\text{DoM}(P, Q)$:



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

Definition

Dominance Move (DoM): Consider that P and Q are two sets of points, with p_i points $i \in \{1, \dots, |P|\}$ and q_j points $j \in \{1, \dots, |Q|\}$. The dominance move of P to Q , $DoM(P, Q)$, is the minimum total distance of moving points of P , such that the moved set $P' = \{p'_1, p'_2, \dots, p'_{|P|}\}$ (with some or all p'_i are allowed to be infeasible) from $P = \{p_1, p_2, \dots, p_{|P|}\}$ dominates Q and that the total move from P to P' must be minimum [1].

The problem is to find P' from P and the total move from P to P' , denoted as $d(p_i, p'_i)$, must be minimum:

$$DoM(P, Q) = \underset{P' \prec Q}{\text{minimize}} \sum_{i=1}^{|P|} d(p_i, p'_i)$$

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

- There is a question regarding its calculation computational cost;
- Algorithm for dominance move calculation was proposed [2]. It is applied only in bi-objectives problem sets;
- DoM authors proposed a calculation approach, but without correct calculation guarantees [3].

Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

Experiments

Conclusion

Future research and
final comments

References

DoM formulation as an assignment problem, and its solution using a mixed-integer programming method [4]:

- An assignment formulation approach;
- A comparative discussion between ϵ -indicators and DoM;
- Some experiments using classical problems sets and some evolutionary algorithms (IBEA, NSGA-II, and SPEA2) using DoM and others quality indicators, such as HV and IGD.

Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

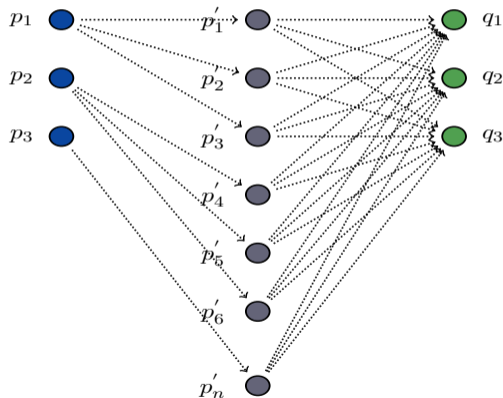
Experiments

Conclusion

Future research and
final comments

References

- A graph that represents the assignment approach:



Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

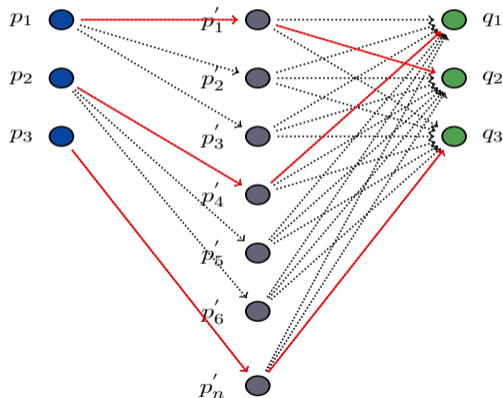
Experiments

Conclusion

Future research and
final comments

References

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Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

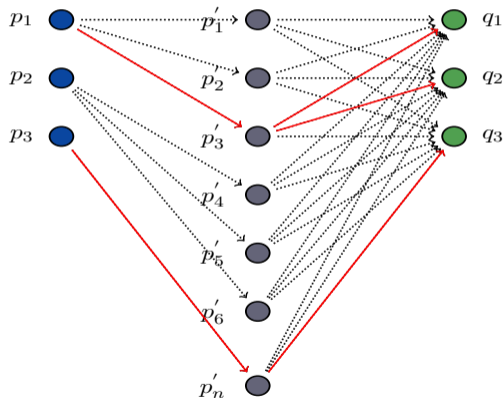
Experiments

Conclusion

Future research and
final comments

References

- A graph that represents the assignment approach:



Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

Experiments

Conclusion

Future research and
final comments

References

The assignments necessary to calculate the formulation turns it prohibitive when the number of solutions in the non-dominated set increase.

Introduction

Introduction

Introduction

Related works

**DoM assignment
formulation and
MIP-DoM**

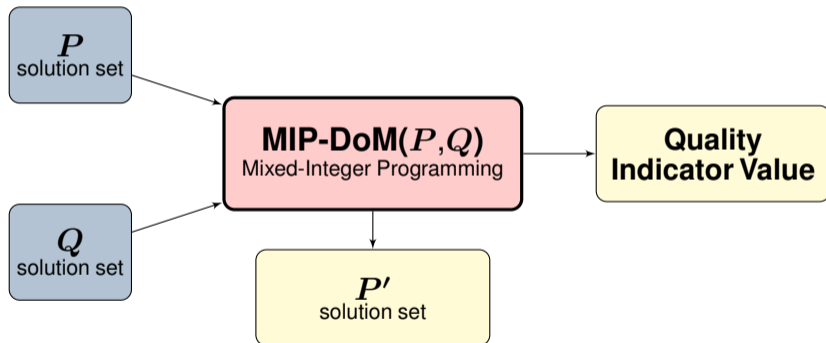
Experiments

Conclusion

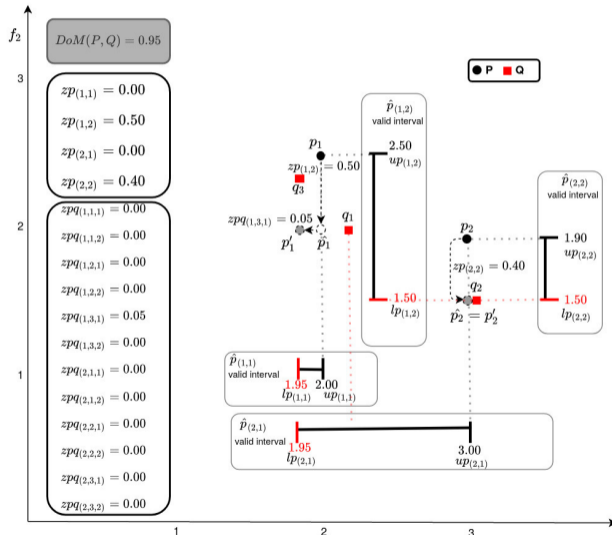
Future research and
final comments

References

MIP-DoM approach :



- Introduction
- Introduction
- Introduction
- Related works
- DoM assignment formulation and MIP-DoM**
- Experiments
- Conclusion
- Future research and final comments
- References



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

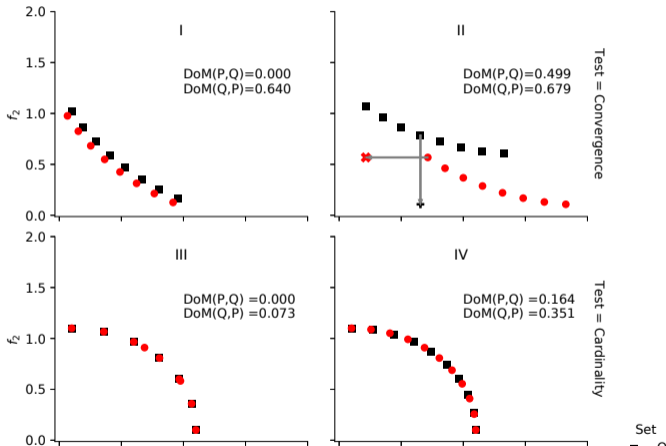
Conclusion

Future research and
final comments

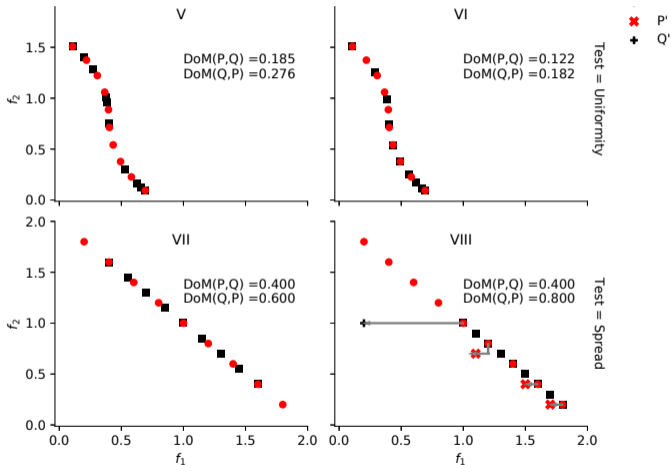
References

- Assessing some solution sets features (*convergence*, *spread*, *uniformity*, and *cardinality*);
- Comparing DoM and ϵ -indicators;
- Testing on more complex test problems - 3 to 30 objectives using till 400 solutions in each set;
- Parametric studies;
- Time-complexity estimates;
- DoM as a running quality indicator.

- Introduction
- Introduction
- Introduction
- Related works
- DoM assignment formulation and MIP-DoM
- Experiments**
- Conclusion
- Future research and final comments
- References

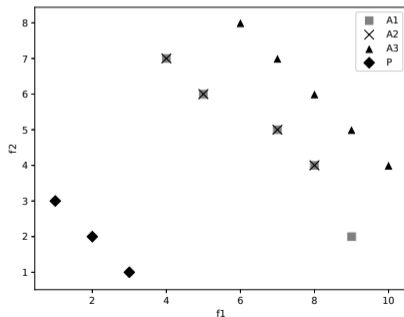


- Introduction
- Introduction
- Introduction
- Related works
- DoM assignment formulation and MIP-DoM
- Experiments**
- Conclusion
- Future research and final comments
- References

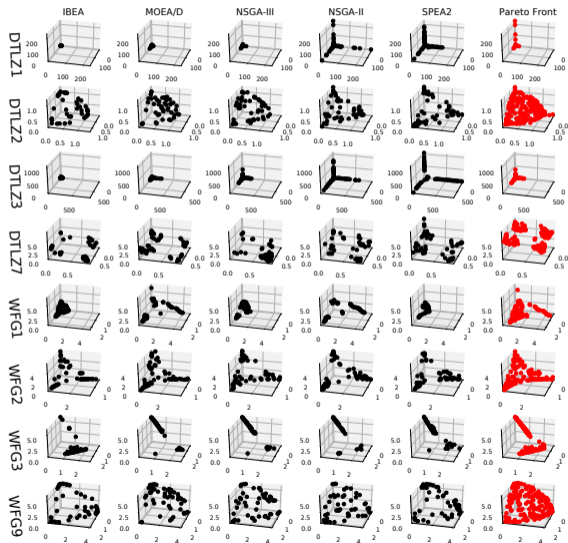


- DoM presents greater values than ϵ -indicators;
- There is an information loss: ϵ -indicators are only related to one particular solution and only one objective in whole solution set, e.g.: two 10-objective solutions, $p_1 = \{0, 0, 0, \dots, 1\}$ and $q_1 = \{1, 1, 1, \dots, 0\}$. The ϵ -additive(p_1, q_1) = ϵ -additive(q_1, p_1) = 1.

| Quality indicator | P solution sets | Q solution sets | | | |
|----------------------------|-----------------|-----------------|--------|--------|--------|
| | | A_1 | A_2 | A_3 | P |
| ϵ -additive | A_1 | 0.000 | 0.000 | -1.000 | 4.000 |
| | A_2 | 2.000 | 0.000 | 0.000 | 4.000 |
| | A_3 | 2.000 | 2.000 | 0.000 | 5.000 |
| | P | -1.000 | -3.000 | -3.000 | 0.000 |
| ϵ -multiplicative | A_1 | 1.000 | 1.000 | 0.900 | 4.000 |
| | A_2 | 2.000 | 1.000 | 1.000 | 4.000 |
| | A_3 | 2.000 | 1.500 | 1.000 | 6.000 |
| | P | 0.500 | 0.428 | 0.333 | 1.000 |
| DoM | A_1 | 0.000 | 0.000 | 0.000 | 9.000 |
| | A_2 | 2.000 | 0.000 | 0.000 | 9.000 |
| | A_3 | 8.000 | 6.000 | 0.000 | 12.000 |
| | P | 0.000 | 0.000 | 0.000 | 0.000 |



- Introduction
- Introduction
- Introduction
- Related works
- DoM assignment
formulation and
MIP-DoM
- Experiments**
- Conclusion
- Future research and
final comments
- References



Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

| Problem set | <i>MIP DoM</i> correlation with | | |
|----------------------|---------------------------------|---------------|---------------------------------------|
| | <i>-HV</i> | <i>IGD+</i> | <i>additive</i> <i>ϵ-indicator</i> |
| DTLZ1 | 0.896 | 0.347* | 0.989 |
| DTLZ2 | 0.770* | 0.769* | 0.783* |
| DTLZ3 | 0.964 | 0.887 | 0.998 |
| DTLZ7 | 0.942 | 0.720* | 0.502* |
| Combined DTLZ | 0.895 | 0.681 | 0.818 |
| WFG1 | 0.265* | 0.019* | 0.256* |
| WFG2 | 0.860 | 0.815* | 0.626* |
| WFG3 | 0.945 | 0.747* | 0.684* |
| WFG9 | 0.627* | 0.093* | 0.226* |
| Combined WFG | 0.674 | 0.372* | 0.448 |
| Combined All | 0.784 | 0.526 | 0.633 |

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

| Problem | MIP-DoM(P, Q) | Value | | |
|----------------|-----------------------------------|------------------|-------------------|-------------------|
| | | $L=100$ $M=5$ | $L=170$ $M=10$ | $L=240$ $M=15$ |
| DTLZ1 | (MOEA/D, NSGA-III) | 1463.461 | 560.182 | 594.894 |
| | (NSGA-III, MOEA/D) | 3401.332 | 6315.371 | 9944.266 |
| DTLZ2 | (MOEA/D, NSGA-III) | 3.943 | 1.175 | 1.065 |
| | (NSGA-III, MOEA/D) | 3.804 | 8.972 | 16.665 |
| DTLZ3 | (MOEA/D, NSGA-III) | 2839.942 | 1878.871 | 2040.851 |
| | (NSGA-III, MOEA/D) | 6418.077 | 15532.120 | 23735.510 |
| DTLZ7 | (MOEA/D, NSGA-III) | 2.502 | 5.543 | 4.745 |
| | (NSGA-III, MOEA/D) | 1.148 | 2.948 | 2.950 |
| WFG1 | (MOEA/D, NSGA-III) | 0.270 | 0.279 | 0.124 |
| | (NSGA-III, MOEA/D) | 0.464 | 0.707 | 0.775 |
| WFG2 | (MOEA/D, NSGA-III) | 2.001 | 1.179 | 1.137 |
| | (NSGA-III, MOEA/D) | 1.571 | 2.423 | 3.665 |
| WFG3 | (MOEA/D, NSGA-III) | 4.524 | 4.678 | 1.955 |
| | (NSGA-III, MOEA/D) | 5.170 | 14.160 | 22.981 |
| WFG9 | (MOEA/D, NSGA-III) | 3.183 | 2.177 | 0.524 |
| | (NSGA-III, MOEA/D) | 4.450 | 13.583 | 31.296 |

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

- Some examples:
 - Considering $M = 2$, $|P| = |Q| = 2$ the model has 16 continuous variables, 22 binary variables, and 60 constraints;
 - Considering $M = 5$, $|P| = |Q| = 200$, there are 202002 continuous variables, 440200 binary variables, and 923400 constraints.
- The Equations to calculate the number of continuous variables, binary variables, and constraints are detailed in the text.

Introduction

Introduction

Introduction

Related works

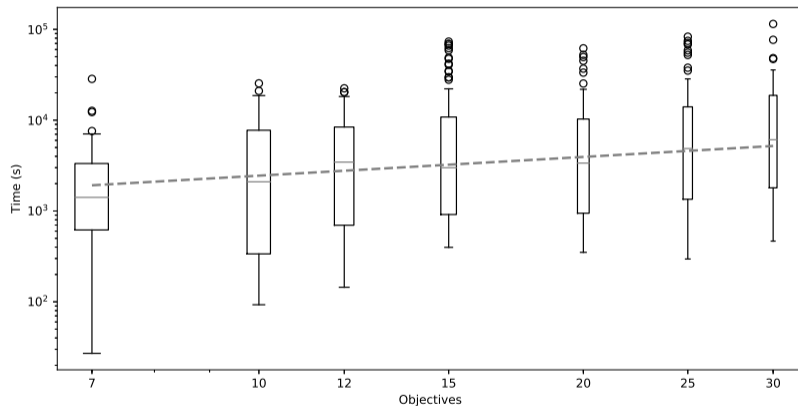
DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References



Linear time behavior $\approx O(M^{0.686})$.

Introduction

Introduction

Introduction

Related works

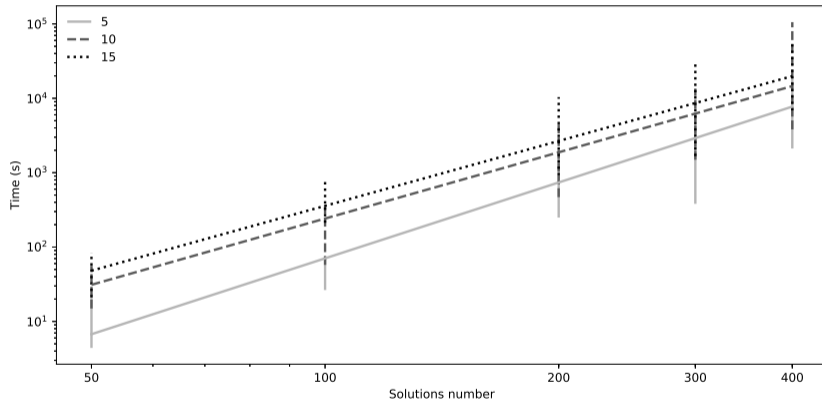
DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References



Polynomial time behavior with $\approx O(L^{3.311})$, $O(L^{2.888})$ and $O(L^{2.833})$.

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

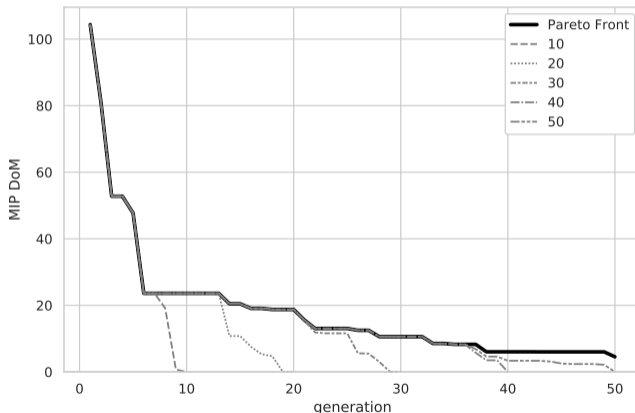
Experiments

Conclusion

Future research and
final comments

References

Termination Criteria.

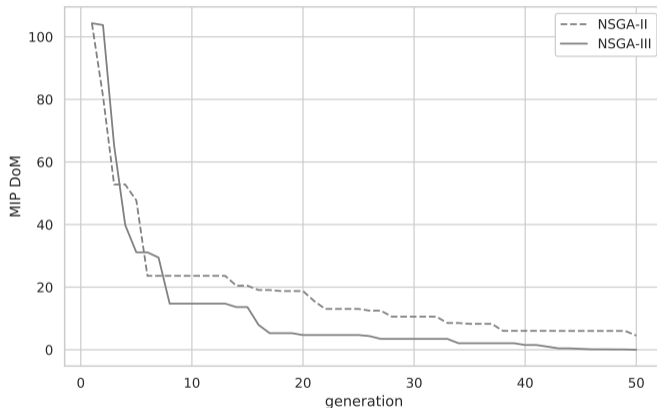


Monotonic decrease in each MIP-DoM curve.

MIP-DoM as running performance indicator

Experiment using DTLZ1 - Comparing two algorithms

- Introduction
- Introduction
- Introduction
- Related works
- DoM assignment formulation and MIP-DoM
- Experiments**
- Conclusion
- Future research and final comments
- References



MIP-DoM(NSGA-II, combined Pareto) in a dashed line;
MIP-DoM(NSGA-III, combined Pareto) in a solid line.

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

- It does not require any reference point or any representative Pareto solution set;
- It is not affected by DRS;
- It overcomes the issue of information loss associated with the ϵ -indicator;
- Presumably, MIP-DoM is compatible in indicating four performance facets between two sets:
 - convergence,
 - spread,
 - uniformity, and
 - cardinality;
- It appears to have a highly Pearson correlation with HV;
- It presents a monotonic decrease in its value, when the first set (Q) is fixed and the second set (P) approaches towards the Pareto front;

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

However, MIP-DoM quality indicator still present some drawbacks:

- MIP-DoM time calculation is more affected by the number of solutions in the set;
- As a running quality indicator, in some cases, the difference in MIP-DoM values between two consecutive generations are in decimal places;
- It demands an efficient MIP solver in its calculation.

Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

**Future research and
final comments**

References

Some possible directions

- An approximate MIP-DoM calculation using a cluster approach (the preliminary results are promising);
- An accelerator operator based on the dominance move;
- The additional information generated by DoM can be applied such as 'direction' in the objective space search.

Introduction

Introduction

Introduction

Related works




DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References

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Introduction

Introduction

Introduction

Related works

DoM assignment
formulation and
MIP-DoM

Experiments

Conclusion

Future research and
final comments

References



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Thank You!



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